

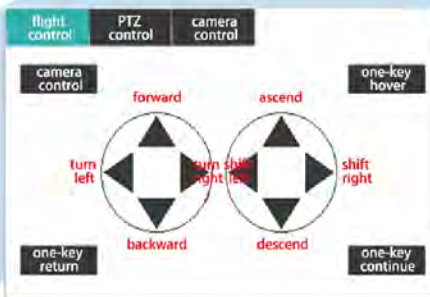
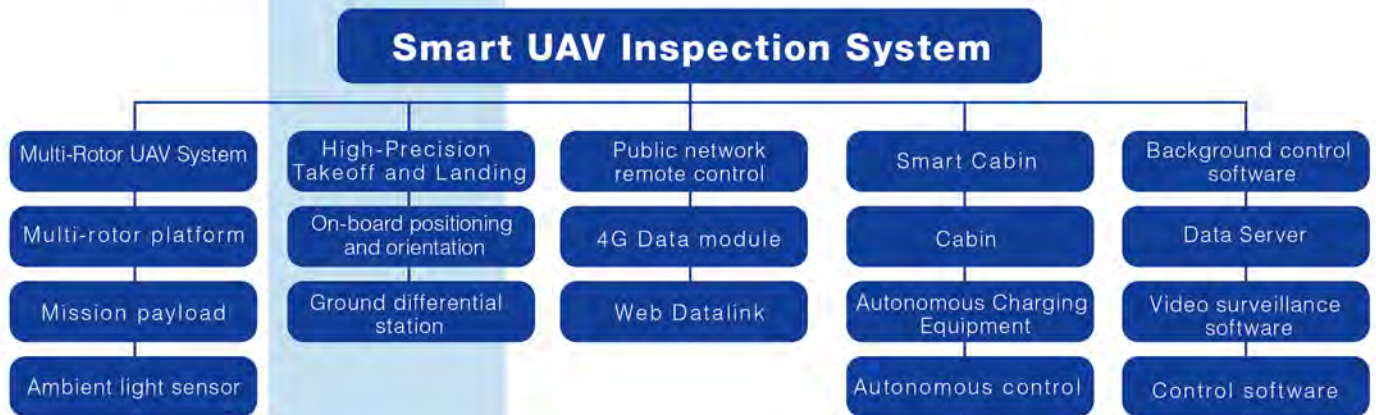


SMART UAV INSPECTION SYSTEM

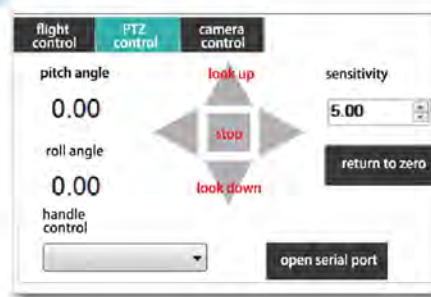


System Introduction

The smart UAV inspection system is a new application mode. Through its application, it can reduce personnel input, improve operational efficiency, provide a strong guarantee for the large-scale promotion of multi-rotor UAV, and provide a more convenient and intelligent solution for applications such as highways, urban roads, security warehouses, oil pipelines, coastal patrols, and other applications.



Aircraft Control Interface



PTZ Camera Control Interface



Payload Control Interface

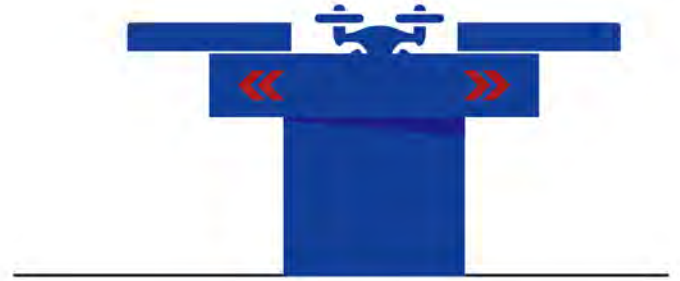
Application Mode

The cabin system is installed along with fixed positions or areas and the number of cabins is more than that of UAVs. Command centers can control single or multiple drones through a specified landing location (take-off and landing points can be different). The UAV generates cruise lines autonomously, the top of the smart cabin opens automatically. The UAV takes off independently and executes inspection tasks, and sends video back to the command center for decision-making.

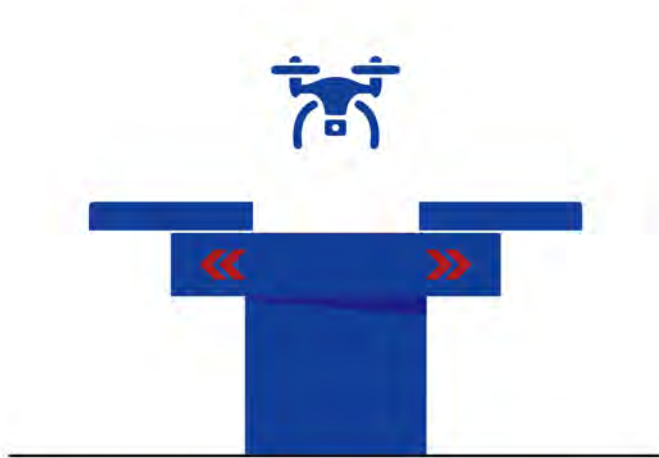
System Demo



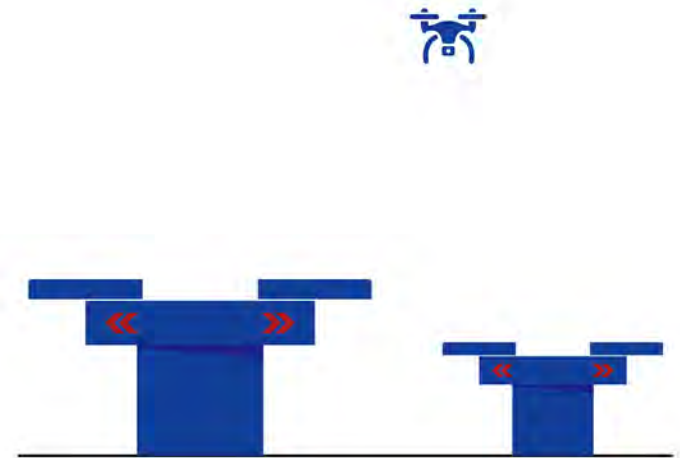
1. Control platform send instructions to Smart Cabin



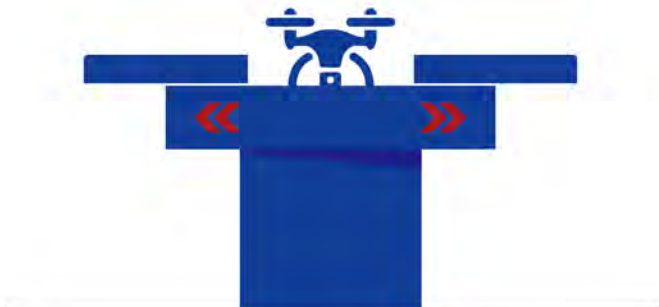
2. Smart Cabin opening



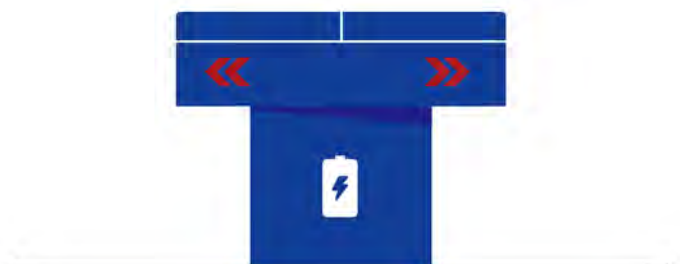
3. Multi-rotor UAV takes off autonomously



4. Cruise operation of multi-rotor UAV



5. Autonomous landing of multi-rotor UAV after completing the operation



6. Smart cabin closes and starts autonomous charging of UAV

System Features



Navigation and Directional
Dual Backup



High-precision take-off
and landing technology



Single-Key control for Takeoff,
Mission, and Landing



Highly intelligent



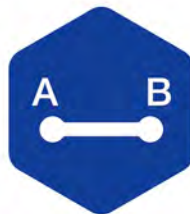
Backstage operation of
multiple UAVs



Strong environmental
adaptability



Remote telemetry 4G control



Point A, B one-way flight



Special requirements can
be customized

Application Scenarios



Environmental monitoring



Pipeline inspection



Border Patrol



Forest fire prevention



Power inspection



Industrial park patrol

Product Parameters

Long-range Multi-rotor UAV

Equipment		System functions and technical parameters
Multi-rotor platform	Head pointing	Significant Head marking
	Diagonal distance	1200mm
	Flight Duration	≥45min (Below 1000m)
	Maximum flight speed	≥40km/h
	Maximum relative flight altitude	≥1000m
	Operating altitude	≥3000m
	Take-off weight (standard payload)	11.5kg
	Maximum payload capacity	5kg
	Operating temperature	-10°C~55°C
	Maximum wind resistance	≥Level 5
	Rainproof ability	Support light rain returning
	Battery	Battery 1 Set
	Control mode	4G remote control
	Basic control	Single-key Take-off, Landing, Hovering, Continuation, Return
Flight control	Black box function	Supports local readings and analysis of flight logs
	Self-check function	Aircraft control module, battery voltage, GPS positioning status above components failure, system lock, cannot fly
	Single-key return	Two ways to return the original route
	Number of waypoints	≥ 200
	Battery voltage emergency alarm	Two-stage voltage alarm function on-ground mapping displays and aircraft, Software alarm of ground station for return Operations when battery voltage is Lower
Precision take-off and landing	Accuracy level of take-off and landing	Accuracy level of take-off and landing ≤0.35m Landing point coordinates can be set to take-off or other points
	Communication Equipment	4G data link
Standard load (Replaceable)		4G data link
		Camera load

Smart Cabin

Mechanical parameters	Size	≤200×160×110 (H) cm
	Weight	≤300kg
	Material	Steel/Aluminum
	Extend diameter	≤4m
Electrical parameters	Input Voltage	200-240V AC
	Power consumption	600W (Peak) /200W (Average)
Environmental perception parameters	Temperature	-30°C~60°C
	Humidity	0~100%
	Wind speed	0~30m/s
	Wind direction	Omnidirectional
	Rainfall	0~50mm/24h
Operational Environment	Working environment	0°C~50°C
	Storage environment	-20°C~80°C
	Communication Mode	4G network
Others	Opening or Close time	≤5 minute
	Protection	Overload, Short Circuit



Smart UAV Inspection System Product Design